ROYAL SRS AND MERCURY SRS

Revised setup procedure for installed orientation, Royal V15 and Mercury V05 and later.

The setup procedure for the **Mercury SRS** has been revised; the automatic detection feature for installed orientation is new as of V15 of the **Royal SRS**.

You will find the following screen displays in the *SETUP ASSISTANT* and also in the *GENERAL SETTINGS* menu under *SET ORIENTATION*:

```
TILT TAIL
UP OR DOWN
[=========]
THEN KEEP STEADY
```

```
SWING TAIL
LEFT OR RIGHT
[=========]
THEN KEEP STEADY
```

The procedure is very simple:

1. At the first screen you are requested to raise or lower the model's tail. You can immediately determine whether the correct axis is selected by observing the elevator's response. If the elevator does not deflect, briefly jerk the model's tail up or down once. The **PowerBox** detects this movement, causing the sensor to switch to the correct axis. Hold the model's tail at a slight angle, so that the bar deflects fully to the right, and wait until the elevator jumps back to the neutral position. The screen now switches automatically to the next display.

2. At this point you are requested to swing the model's tail to left or right: the rudder should immediately deflect in response to this movement. Here again: if the rudder does not respond, briefly jerk the model's tail once to left or right, so that the sensor switches to the correct axis. Now hold the model's tail far enough to left or right to cause the bar to move to full deflection, and wait until the rudder jumps back to the neutral position. This concludes the procedure, and the following screen display appears:

```
MOUNTING
ORIENTATION
DETECTED
```

Check once more that the installed orientation is correct before test-flying the **iGyro** using the *TESTFLY ASSISTANT.*